APX-18 UAV

SINGLE BOARD DUAL ANTENNA GNSS-INERTIAL SOLUTION

The Trimble APX-18 UAV is an OEM GNSS-Inertial solution with dual GNSS antenna input, designed to georeference LIDAR and other imaging data when collected from Unmanned Aerial Vehicles (UAV) at low speeds or when hovering. Comprised of a small single OEM board containing a precision GNSS receiver with two antenna heading and inertial sensor components plus POSPac UAV Differential GNSS-Inertial office software, the Trimble APX-18 UAV produces a highly accurate position and orientation solution for directly georeferencing LIDAR point clouds and imagery.

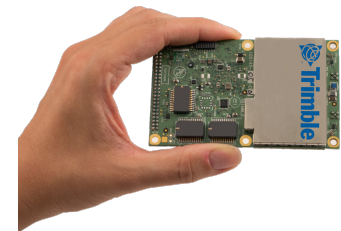### HIGH ACCURACY, EXTREMELY SMALL PACKAGE

Measuring just 100 x 60 mm and weighing only 62 grams, the APX-18 UAV provides unparalleled performance in an extremely small package. With the included POSPac UAV post-mission software, it produces a highly accurate position and orientation solution for direct georeferencing of cameras, LIDARs and other UAS sensors.

THE APX-18 UAV BRINGS ALL THE BENEFITS OF DIRECT GEOREFERENCING TO UAV PLATFORMS:

- ▶ Turn your UAV into a professional mapping solution
- ▶ Ultra-fast image georeferencing for faster map production and delivery
- ▶ Reduced number of ground control points, saving time and money
- ▶ Consistent, reliable, highly accurate results
- ▶ Increased collection area per flight for greater productivity
- ▶ Redundant navigation solution to autopilot for enhanced safety

Key Features

- ▶ High-performance Direct Georeferencing solution for improved efficiency and accuracy of mapping from small Unmanned Aerial Vehicles
  - • Reduce/eliminate GCP's
  - • Reduce sidelap
  - • Accurate LIDAR georeferencing
  - • Instant alignment through dual GNSS antenna heading
- ▶ Compact single-board OEM module complete with survey-grade multi-frequency GNSS receiver and MEMS inertial components
- ▶ Applanix IN-Fusion™ GNSS-Inertial and SmartCal™ compensation technology for superior position and orientation performance
- ▶ POSPac UAV Differential GNSS Inertial post-processing software for highest accuracy
- ▶ RTK real-time position for precision landing applications
- ▶ Supports all common RTK corrections such as CMR, CMR+, RTCM

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TRANSFORMING THE WAY THE WORLD WORKS

Trimble

APX-18 UAV

TECHNICAL SPECIFICATIONS
System Summary
- Advanced Applanix IN-Fusion™ GNSS-Inertial integration technology
- Solid-state MEMS inertial sensors with Applanix SmartCal™ compensation technology
- Advanced Trimble Maxwell Custom GNSS survey technology with 2x336 tracking channels
- Primary Antenna
  - GPS: L1 C/A, L2C, L2E, L5
  - GLONASS: L1 C/A, L2 C/A, L3 CDMA[8]
  - BeiDou: B1, B2, B3
  - Galileo[1]: E1, E5A, E5B, E5AltBOC, E6[8]
  - IRNSS: L5
  - QZSS: L1 C/A, L1 SAIF, L1C, L2C, L5, LEX
  - SBAS: L1 C/A, L5
  - MSS L-Band: Trimble RTX, OmniSTAR

- Secondary Antenna
  - GPS: L1 C/A, L2C, L2E, L5
  - GLONASS: L1 C/A, L2 C/A, L3 CDMA[8]
  - BeiDou: B1, B2, B3
  - Galileo[1]: E1, E5A, E5B, E5AltBOC, E6[8]
  - IRNSS: L5
  - QZSS: L1 C/A, L1 SAIF, L1C, L2C, L5, LEX
- High precision multiple correlator for GNSS pseudorange measurements
- Unfiltered, unsmoothed pseudorange measurements data for low noise, low multipath error, low time domain correlation and high dynamic response
- Very low noise GNSS carrier phase measurements with <1 mm precision in a 1 Hz bandwidth
- Proven Trimble low elevation tracking technology
- 100 Hz position, roll, pitch and heading output
- IMU data rate 200 Hz
- Navigation output format: ASCII (NMEA-0183), Binary (Trimble GSOF)
- Supported Reference input: CMR, CMR+, sCMRx, RTCM 2.1, 2.2, 2.3, 3.0, 3.1, 3.2
- Support for POSPac UAV post-processing software (included)
- No export permit required

LAN INPUT/OUTPUT
All Ethernet functions are supported through dedicated IP address (Static or DNS) simultaneously including web based control GUI access and real time data streaming.

TCP/IP and UDP	ASCII and Binary data streaming (Time tag, PPS sync, status, position, attitude, velocity, track and speed, dynamics, performance metrics, GNSS data)
HTTP	Web based Control software (GUI) for easy system configuration and low rate display. Support for all common browsers (IE, Safari, Mozilla, Google Chrome, Firefox)

SERIAL INPUT/OUTPUT
2 x RS232 ports (baud rates up to 460,800)

Parameters	ASCII and Binary data streaming (Time tag, PPS sync, status, position, attitude, velocity, track and speed, dynamics, performance metrics, GNSS data), reference input (CMR, CMR+, sCMRx, RTCM), configuration messages

OTHER INPUT/OUTPUT
PPS (pulse-per-second)	Time Sync Pulse output
Event Input (2)	Two time mark of external events
	TTL 3.3 V pulses, max rate 50 Hz

1 Developed under a License of the European Union and the European Space Agency
2 Typical performance. Actual results are dependent upon satellite configuration, atmospheric conditions and other environmental effects
3 Typical survey mission profile, max RMS error. The heading error assumes minimum of 1m antenna separation.
4 Requires base station and radio link, sold separately
5 POSPac UAV, short base line operation
6 Sensor bandwidth (-3 dB amplitude) ~ 50 Hz
7 Sold separately
8 There is no official GLONASS L3CDMA or Galileo E6 ICD. The current tracking capability is based on publicly available information. Full receiver compatibility cannot be guaranteed.
9 The hardware of this product is designed for BeiDou B3 compatibility (trial version) and its firmware will be enhanced to fully support such new signal as soon as officially published ICD becomes available.

Digital I/O (3)   LED drivers with dedicated functionality for systems integrators

LOGGING
Internal Logging	6 GByte Flash memory
External Logging	USB 2.0 Device port
Parameters	Timetag, status, position, attitude, velocity, track and speed, dynamics, performance metrics, raw IMU data (200 Hz), raw GNSS data (5 Hz)

PERFORMANCE SPECIFICATIONS[2] (RMS ERROR)
Unmanned Airborne Vehicle Applications

	SPS	DGPS	RTK[4]	Post-Processed[5]
Position (m)	1.5 - 3.0	0.5 - 2.0	0.02 - 0.05	0.02 - 0.05
Velocity (m/s)	0.05	0.05	0.02	0.015
Roll & Pitch (deg)	0.04	0.03	0.03	0.025
True Heading[3] (deg)	0.15	0.12	0.10	0.080

PHYSICAL CHARACTERISTICS
Size	100 L x 60 W x 11.6 H mm (nominal)
Weight	62 grams
Power	3.3 V DC +5%/-3%, typical power consumption of 1.5W (L1/L2 GPS + L1/L2 GLONASS)
Connectors	I/O: 44 Pin Header Samtec TMM-122-03-S-S-MW (mating part FCI 90311-044LF)
Antenna Port:	Connector: 2 x MMCX receptacle
	Output Voltage: 3.3 V DC to 5 V DC
	Maximum Current: 400 mA
	Minimum Input Signal Strength: 32dB (>35 dB Recommended)

ENVIRONMENTAL CHARACTERISTICS
Temperature:	-40 deg C to +75 deg C (Operational)
	-55 deg C to +85 deg C (Storage)
Measurement Range:	+/- 6g[6], +/- 300 dps
Mechanical Shock:	+/- 75g Survival
Operating Humidity:	5% to 95% R.H. non-condensing at +60 deg C
Maximum Operating Limits:	515 m/sec
	18,000 m

ADDITIONAL ACCESSORIES[7]
Evaluation Kit (includes development board and power supply)

POSPAC UAV OFFICE SOFTWARE
- Post-processed Differential GNSS-Inertial SW for APX-18
- 200 Hz Navigation solution (Position, Velocity, Orientation, Rates, Accelerations)
- Applanix IN-Fusion GNSS-Integration technology
- Full support for UAV dynamic models
- Single Base Differential GNSS-Inertial processing
- Support for Applanix SmartBase virtual reference station module[7]
- Forward and reverse processing with optimal Smoother

Specifications subject to change without notice.

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