POS AVX 210

KEY FEATURES

Cost effective and high-performance Direct Georeferencing solution for improved efficiency and high accuracy of mapping with small and medium format digital cameras and low altitude LiDAR sensors

Reduce/eliminate GCP's Reduce Sidelap

Compact and rugged enclosure with survey-grade multi-frequency GNSS receiver and MEMS inertial components

Applanix IN-Fusion™ GNSS-Inertial and SmartCal™ compensation technology for superior position and orientation performance

Compatible with TrackAir Flight Management System (NanoTrack)

Supported by POSPac MMS industry leading software for Direct Georeferencing of airborne mapping sensors

RTK position combined with highaccuracy orientation

POS AVX 210 GNSS-INERTIAL SOLUTION FOR EFFICIENT, HIGH-ACCURACY MAPPING

The Applanix POS AVX 210 is a GNSS-Inertial solution designed to reduce the cost and improve the efficiency of mapping with small and medium format cameras. The single rugged enclosure contains a precision GNSS receiver and inertial sensor components, logging capability, interface for mapping sensors and TrackAir Flight Management System. The POS AVX 210 is fully supported by POSPacMMS, powerful GNSS/Inertial processing software featuring the advanced Applanix SmartBaseTM and Applanix In-FusionTM technology for increased productivity.

Performance You Can Trust

capture everything. precisely.







TECHNICAL SPECIFICATIONS

- $Advanced\ Applanix\ IN\text{-}Fusion^{\text{\tiny{TM}}}\ GNSS\text{-}Inertial\ integration\ technology}$
- Solid-state MEMS inertial sensors with Applanix SmartCal™ compensation technology
- Advanced Trimble GNSS survey technology
- 336 Channels
- GPS: L1 C/A, L2C, L2E, L5
- GLONASS: L1 C/A, L2 C/A, L3 CDMA
- BeiDou: B1, B2
- Galileo¹: E1, E5A, E5B, E5AltBOC
- QZSS: L1 C/A, L1 SAIF, L2C, L5
- SBAS: L1 C/A, L5
- High precision multiple correlator for GNSS pseudorange measurements
- Unfiltered, unsmoothed pseudorange measurements data for low noise, low multipath error, **PHYSICAL CHARACTERISTICS** low time domain correlation and high dynamic response
- Very low noise GNSS carrier phase measurements with <1 mm precision in a 1 Hz bandwidth Si
- Proven Trimble low elevation tracking technology
- 100Hz real-time position and orientation output
- IMU data rate 200 Hz
- Navigation output format: ASCII (NMEA-0183), Binary (Trimble GSOF)
- Supported Reference input: CMR, CMR+, sCMRx, RTCM 2.1, 2.2, 2.3, 3.0, 3.1
- Support for POSPac MMS post-processing software (sold separatey)
- No export permit required

LAN INPUT/OUTPUT

All Ethernet functions are supported through dedicated IP address (Static or DNS) simultaneously.

TCP/IP and UDP ASCII and Binary data streaming (Time tag, PPS sync, status, position,

attitude, velocity, track and speed, dynamics, performance metrics, GNSS

HTTP Web based Control software (GUI) for easy system configuration and low

rate display. Support for all common browsers (IE, Safari, Mozilla, Google

Chrome, Firefox)

LOGGING:

Internal Logging 6 GByte Flash memory **External Logging** USB 2.0 Device port

Parameters Time tag, status, position, attitude, velocity, track and speed, dynamics,

performance metrics, raw IMU data (200 Hz), raw GNSS data (5 Hz).

PERFORMANCE SPECIFICATIONS² (RMS ERROR)

Airborne

	SPS	DGPS	RTK⁴	Post-Processed ⁵
Position (m)	1.5 - 3.0	0.5 - 2.0	0.02 - 0.05	0.02 - 0.05
Velocity (m/s)	0.05	0.05	0.02	0.015
Roll & Pitch (deg)	0.04	0.03	0.03	0.025
True Heading ³ (deg)	0.30	0.28	0.18	0.080

Board Set

Boulu Set	
n Size	
Weight	0.66 kg
Power	Wide range input 8-28 V DC, typical power
	consumption of 3.5W at room temperature
Connectors	
	Antenna: TNC (Female)
GNSSAntenna I NA Power Input:	AV39 included

ENVIRONMENTAL CHARACTERISTICS

Temperature:	40 deg C to +75 deg C (Operational)
	-55 deg C to +85 deg C (Storage)
Measurement Range:	+/- 6g ⁶ , +/- 300 dps
Mechanical Shock:	+/- 75g Survival
Operating Humidity:	5% to 95% R.H. non-condensing at +60 deg C
Maximum Operating Limits	515 m/sec
	18,000 m
IP rating:	IP67

- (1) Developed under a License of the European Union and the European Space Agency
- (2) Typical performance. Actual results are dependent upon satellite configuration, atmospheric conditions and other environmental effects
- (3) Typical survey mission profile, max RMS error, Heading error will increase for low speed rotor applications and when hoverina.
- (4) Requires base station and radio link, sold separately
- (5) Post-Processed with POSPac MMS
- (6) Sensor bandwidth (-3 dB amplitude) ~ 50 Hz

SERIAL INPUT/OUTPUT

2 x RS232 ports

Parameters ASCII and Binary data streaming (Time tag, PPS sync, status, position,

attitude, velocity, track and speed, dynamics, performance metrics, GNSS Specifications subject to change without notice.

data), reference input (CMR, CMR+, sCMRx, RTCM), configuration messages.

Other I/O

PPS(pulse-per-second) Time Sync Pulse output Event Input (2) Two time mark of external event.

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